

Radar-based Dataset Development for Human Activity Recognition

A. Ahmed and Y. D. Zhang

Advanced Signal Processing Laboratory, Temple University, Philadelphia, Pennsylvania, USA
{ammar.ahmed, ydzhang}@temple.edu

Human activity recognition (HAR) is an important research problem and considerable efforts have been made in the past two decades to develop successful solutions. Datasets developed for HAR serve as a baseline for evaluating new HAR algorithms and play a pivotal role in advancing the research efforts in this domain. Hundreds of datasets have been developed by various researchers which focus on different types of motions and activities [1]. In this context, most of the efforts have been invested in developing the datasets which contain either the video or clips of 2D images of different types of motions. Due to the advent of 3D sensors, modern datasets also contain the information of the motion as well as the depth [2].

There are several intrinsic challenges associated with image- or video-based HAR. The HAR strategies developed based on visual datasets cannot work for challenging visibility conditions or in the absence of light. There are also privacy concerns associated with image- and video-based HAR.

These facts have motivated great interest to develop radar-based HAR methods [3]. Such efforts are still in an early phase and generally exploit Doppler and micro-Doppler analysis of radar signals reflected by the human body. The basic idea is that different human activities exhibit unique Doppler and micro-Doppler signatures which can be classified by using their time-frequency characteristics. Recently, cost-effective millimeter-wave radar systems with high Doppler sensitivity enabled easier access to detecting and classifying human activities. Since the received micro-Doppler signals do not provide facial and other sensitive privacy information, radar-based HAR is much more easily accepted without privacy-related concerns.

In this abstract, we present a radar-based dataset for human activity recognition (Rad-HAR) that exploits continuous-wave (CW) radar signals. The dataset is collected for scenarios where one human subject makes different motions in front of the radar. For this purpose, we use the Ancortek SDR-KIT-2500 [4] software-defined transmitter-receiver system which consists of one transmitter and one receiver as shown in Figure 1. CW signals with carrier frequency of 25 GHz are used for the dataset development. We provide the raw as well as processed micro-Doppler signals in the DAT format which can be imported in several popular programming languages. Several MATLAB examples are provided to perform data processing exploiting time-frequency analysis techniques.



Figure 1. Ancortek SDR-KIT-2500 module [4].

Signal Model: Consider a human body as the collection of P point targets, which are located in the front of the radar. The transmit radar signal is given by:

$$s(t) = A \exp(j2\pi f_c t), \quad (1)$$

where A is the transmit signal amplitude, f_c is the carrier frequency, and t is the fast time. The instantaneous range of the p th point target with respect to the radar is:

$$R_p(t) = R_{0,p} + \int_{t_0}^t v_p(u) \cos(\varphi_p(u)) du, \quad (2)$$

where t_0 is the start time, $R_{0,p}$ is the initial range of the p th point target, whereas $v_p(t)$ and $\varphi_p(t)$ respectively denote the velocity and angle of the p th target at time instant t with respect to the radar.

Subsequently, the signal reflected by p th point target is expressed as:

$$r_p(t) = A_p(t) \exp(j2\pi f_c(t - \tau_p)) = A_p(t) \exp\left(j2\pi f_c\left(t - \frac{2R_p(t)}{c}\right)\right), \quad (3)$$

where $A_p(t)$ is the amplitude of the target echo at time t which depends on the transmit signal amplitude A , the range $R_p(t)$, and the radar cross-section of the point target. Moreover, $\tau_p = 2R_p(t)/c$ is the time delay due to the round-trip range of the p th point target, and c is the electromagnetic propagation speed.

Using Eq. (3) and the known carrier frequency f_c , we can extract the baseband signal received corresponding to the p th point target as:

$$\bar{r}_p(t) = r_p(t)A_c \exp(-j2\pi f_c t) = B_p(t) \exp\left(-j4\pi f_c \frac{R_p(t)}{c}\right), \quad (4)$$

where A_c is the amplitude of the demodulating carrier waveform and $B_p(t)$ is the baseband amplitude of the resulting received signal. The time-varying Doppler frequency corresponding to the p th point target is expressed as:

$$f_{D,p}(t) = -\frac{2v_p(t) \cos \varphi_p(t)}{c} f_c = -2 \frac{f_c}{c} \frac{d}{dt} R_p(t). \quad (5)$$

Since the human body is the collection of all point targets contained in the set P , the overall baseband signal corresponding to the entire human body is represented by the collection of signals from all these point targets, given by:

$$\bar{r}(t) = \int_{p \in P} \bar{r}_p(t) dp = \int_{p \in P} B_p(t) \exp\left(-j4\pi f_c \frac{R_p(t)}{c}\right) dp. \quad (6)$$

The velocities of different body parts generally differ from each other. In this context, time-frequency analysis is suitable to characterize the resulting Doppler and micro-Doppler signatures. In this abstract, spectrogram generated from the short-time Fourier transform is adopted, expressed as:

$$S_{\bar{r}}(t, f) = \left| \int_{-\infty}^{\infty} \bar{r}(t) h(t - k) e^{-j2\pi f k} dk \right|^2, \quad (7)$$

where $h(t)$ is a suitable window function.

Dataset: The Rad-HAR dataset was acquired at the Advanced Signal Processing Laboratory (ASP Lab) of Temple University. The data collection was approved by the Institutional Review Board (IRB) of Temple University. The layout of the laboratory is given in Figure 2. The dataset consists of six different types of human movements as shown in Table 1. Data due to the human motions are recorded at different sampling rates and stored as raw data in the DAT file format. The data for each type of motion are placed in separate folders with folder name acting as the data label. These files contain raw in-phase and quadrature (I/Q) data in the form of complex sinusoids expressed in Eq. (6).

The Rad-HAR dataset also contains processed data. For such processed data, the direct-

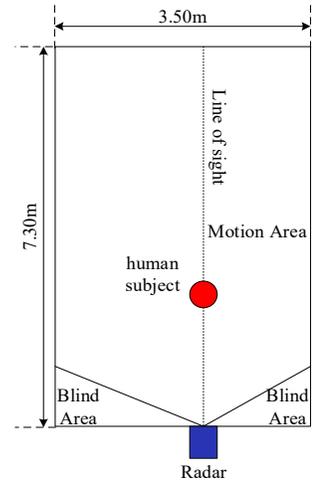


Figure 2. The lab environment in which the Rad-HAR dataset is acquired.

Table 1. The Rad-HAR Dataset

	Type of motions	Raw data length (sec)	Raw data sample rate (ksample/sec)	Number of three-second data segments
Facing towards the radar	Boxing	60/30	512	196
	Clapping	15/180	128/512	199
	Hand waving	60/30/15	512/512/128	199
	Piaffe / Mark time	15/300	128/512	199
	Running towards radar	3/6	128/128	50
	Walking towards radar	3/6	512/128	100
Facing opposite to the radar	Walking away from radar	6	128	50
	Running away from radar	6	128	97

current (DC) offset is removed because it mainly represents strong clutter near 0 Hz in the Doppler domain and obscures target motion recognition. Furthermore, we clip the data of each class into three-second segments which can be readily employed to observe the Doppler signatures in the time-frequency domain. We downsampled all the processed data to 64 ksamples/sec which is high enough to capture the desired human motions.

Instruction to accessing the Rad-HAR dataset is provided at [5] under the “Resources” section.

Examples: As an example to accessing the Rad-HAR dataset, we present the time-frequency characteristics of selected received radar signals. The spectrogram computed for the first three seconds of the data in each class is shown in Figure 3. It is evident that each class has unique Doppler and micro-Doppler signatures for them to be separately recognized. For motions that generate noticeable changes in the range between the target and the radar, such as walking and running, the spectrogram clearly reflects that the propagation loss of the radar signals increases with the range. An example of the HAR performance on the Rad-HAR dataset by exploiting deep learning approaches can be found in [6].

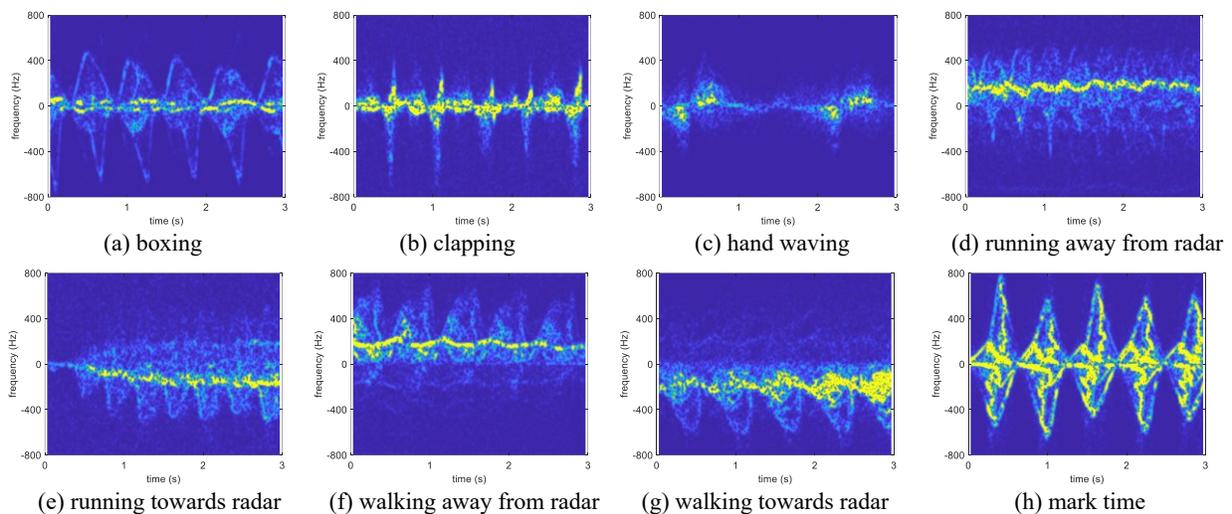


Figure 3. Spectrogram of different types of motions with respect to radar in Rad-HAR dataset

ACKNOWLEDGEMENT

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RADAR-BASED DATASET DEVELOPMENT FOR HUMAN ACTIVITY RECOGNITION

Ammar Ahmed and Yimin D. Zhang

Advanced Signal Processing Laboratory, Temple University, Philadelphia, Pennsylvania, USA



BACKGROUND

Datasets for Human Activity Recognition

- Human activity recognition (HAR) is an important research problem and considerable efforts have been made in the past two decades to develop successful solutions.
- Datasets developed for HAR serve as a baseline for evaluating HAR algorithms and play a pivotal role in advancing the research efforts in this domain.
- Most of the efforts in this domain have been invested in developing the vision-based datasets which contain either video or clips of 2D images of different types of motions.

Challenges for Vision-based HAR Datasets

- There are several intrinsic challenges associated with vision-based HAR.
- Vision-based HAR strategies cannot work under challenging visibility conditions or in the absence of light.
- There are privacy concerns associated with vision-based HAR.

Advantages of Radar-based HAR

- Radar-based HAR has the following advantages:
- Radar-based HAR is much more easily accepted without privacy-related concerns because radar signals do not provide facial and other sensitive privacy information.
- Radar-based HAR is not affected by the visibility conditions.
- Recent advances in millimeter-wave radar systems provide high Doppler sensitivity with a low cost.

TRANSMIT RADAR SIGNAL

The continuous-wave transmit signal by the radar can be expressed as:

$$s(t) = A \exp(j2\pi f_c t), \quad (1)$$

where

A : transmit signal amplitude
 f_c : carrier frequency
 t : fast time

We use Ancoartek SDR-KIT-2500 software-defined transmitter-receiver system for Rad-HAR dataset development. This kit consists of one transmitter and one receiver as shown in Figure 1.



Figure 1. Ancoartek SDR-KIT-2500 module [3].

Consider a human body as the collection of P point targets located in the front of the radar. The instantaneous range of the p th point target with respect to the radar is:

$$R_p(t) = R_{0,p} + \int_{t_0}^t v_p(u) \cos(\varphi_p(u)) du, \quad (2)$$

where

t_0 : start time,
 $R_{0,p}$: initial range of the p th point target with respect to the radar
 $v_p(t)$: instantaneous velocity of the p th target with respect to the radar at time instant t
 $\varphi_p(t)$: instantaneous angle of the p th target with respect to the radar at time instant t

DOPPLER SIGNATURE ANALYSIS

The time-varying Doppler frequency corresponding to the p th point target is expressed as:

$$f_{D,p}(t) = -\frac{2v_p(t) \cos \varphi_p(t)}{c} f_c = -2 \frac{f_c}{c} \frac{d}{dt} R_p(t). \quad (5)$$

Since the human body is the collection of all point targets contained in the set P , the overall baseband signal corresponding to the entire human body is represented by the collection of signals from all these point targets, given by:

$$\bar{r}(t) = \int_{p \in P} \bar{r}_p(t) dp = \int_{p \in P} B_p(t) \exp(-j4\pi f_c \frac{R_p(t)}{c}) dp. \quad (6)$$

The velocities of different body parts generally differ from each other. In this context, time-frequency analysis is suitable to characterize the resulting Doppler and micro-Doppler signatures.

We provide the examples of the Doppler signatures generated due to different human activities. Spectrogram generated from the short-time Fourier transform is adopted for this purpose, expressed as:

$$S_r(t, f) = \left| \int_{-\infty}^{\infty} \bar{r}(t) h(t-k) e^{-j2\pi f k} dk \right|^2, \quad (7)$$

where $h(t)$ is a suitable window function.

LABORATORY LAYOUT

The Rad-HAR dataset was acquired at the Advanced Signal Processing Laboratory (ASP Lab) of Temple University. The data collection was approved by the Institutional Review Board (IRB) of Temple University. The layout of the laboratory is given in Figure 2.

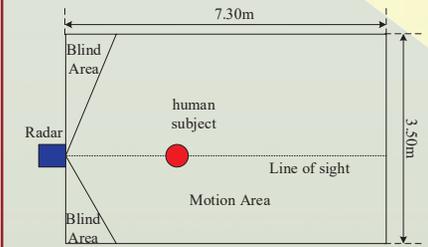


Figure 2. The lab environment in which the Rad-HAR dataset is acquired.

REFERENCES

- [1] M. Wang, Y. D. Zhang, and G. Cui, "Human motion recognition exploiting radar with stacked recurrent neural network," Digital Signal Processing, vol. 87, pp. 125-131, April 2019.
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EXAMPLES OF DOPPLER SIGNATURES FROM RAD-HAR DATASET

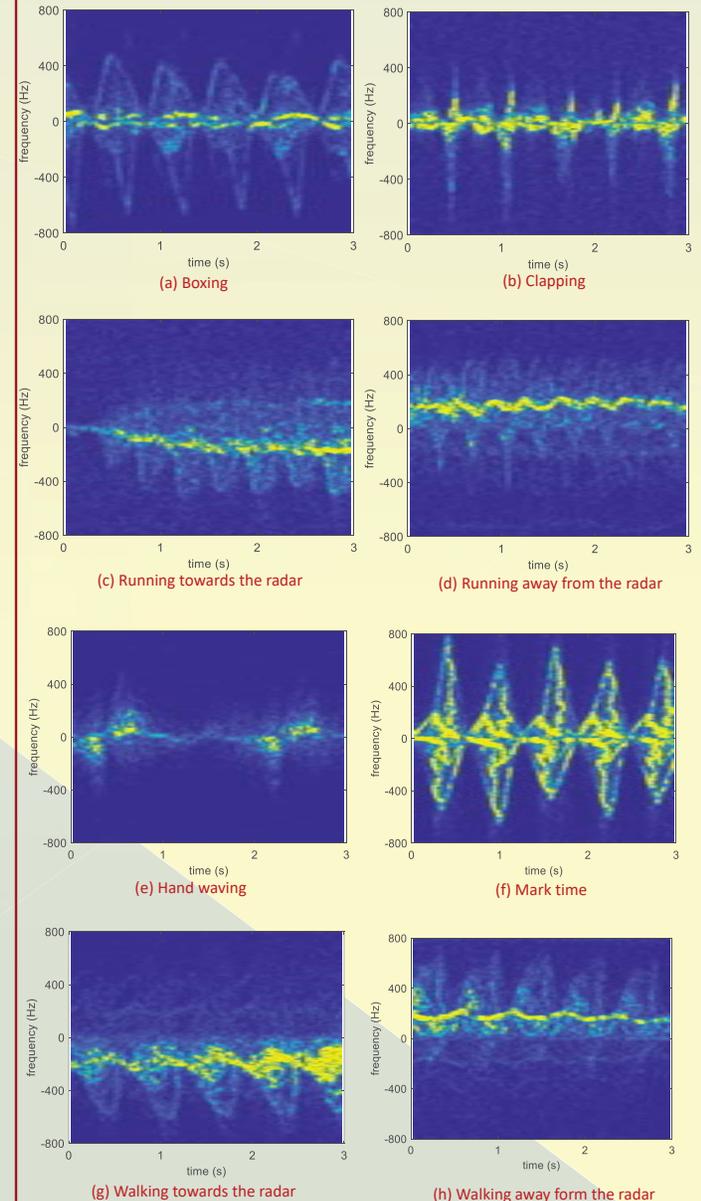


Figure 3. Spectrogram of signals with different types of motions in Rad-HAR dataset.

RAD-HAR DATASET

The advantages inherited by radar-based HAR have driven great interest to develop radar-based HAR (Rad-HAR) dataset.

The motivation for developing Rad-HAR dataset is:

- Different human activities exhibit unique Doppler and micro-Doppler signatures which can be revealed by their time-frequency representations.
- Modern machine learning algorithms enable human motion recognition based on their unique time-frequency characteristics [1].

The Rad-HAR dataset is collected for scenarios where one human subject makes different motions in front of the radar. Main features of Rad-HAR dataset are as follows:

- Continuous-wave signals with carrier frequency of 25 GHz are used.
- We provide raw as well as processed radar signals in the DAT format which can be imported in several popular programming platforms like MATLAB and Python.
- Raw and processed radar signals can be directly exploited by modern machine learning algorithms for research activities related to HAR.
- MATLAB examples are provided to perform data processing exploiting time-frequency analysis techniques. The Rad-HAR dataset can be accessed online at [2].

RECEIVED RADAR SIGNAL

The received signal corresponding to the p th point target is expressed as:

$$r_p(t) = A_p(t) \exp(j2\pi f_c (t - \tau_p))$$

$$= A_p(t) \exp(j2\pi f_c (t - \frac{2R_p(t)}{c})), \quad (3)$$

where

$A_p(t)$: instantaneous amplitude of the target echo at time t
 $\tau_p = 2R_p(t)/c$: time delay due to the round-trip range of the p th point target
 c : electromagnetic propagation speed

Using Eq. (3) and the known carrier frequency f_c , we can extract the received baseband signal corresponding to the p th point target as:

$$\bar{r}_p(t) = r_p(t) A_c \exp(-j2\pi f_c t)$$

$$= B_p(t) \exp(-j4\pi f_c \frac{R_p(t)}{c}), \quad (4)$$

where

A_c : amplitude of the demodulating carrier waveform
 $B_p(t)$: instantaneous baseband amplitude of the received signal at time t