

Solutions for Test 1

Problem No. 1

(a)

$$H(X) = \frac{3}{8} \log \frac{8}{3} + \frac{5}{8} \log \frac{8}{5} = H(Y) = 0.954 \quad \text{bits}$$

(b)

$$\begin{aligned} H(X, Y) &= \sum_x \sum_y p(x, y) \log \frac{1}{p(x, y)} \\ &= \frac{1}{8} \log 8 + \frac{2}{8} \log 4 + \frac{4}{8} \log 2 + \frac{1}{8} \log 8 = 1.75 \quad \text{bits} \end{aligned}$$

(c)

$$H(X|Y) = H(X, Y) - H(X) = 1.75 - 0.954 = 0.796 \quad \text{bits}$$

(d)

$$H(X, Y) > H(Y|X)$$

Joint entropy is the entropy of one random variable plus the conditional entropy of the other random variable given the first random variable.

Problem No. 2

(a)

Table 1 Probability of Wins

P(A)	Match,n
0	1
0.5	2
0.67	3
0.75	4
0.8	5
0.83	6
0.86	7
0.88	8

Playing three matches would not be a good choice because Tiger can not win the first match and the second match could equally go either way. Tiger would not want the game to end up in a tie; therefore, we rule out the possibility of playing four matches. In five matches, Tiger is favored to win three matches, and he chances of winning increases with each successive match. Tiger should play at least five matches in order to maximize his wins.

(b)

$$H(X) = P(A)\log\frac{1}{P(A)} + (1 - P(A))\log\frac{1}{(1 - P(A))}$$

Table 2 Entropy

X	H(X)
1	0
2	1
3	.918
4	.811
5	.722
6	.650
7	.592
8	.544

H(1) - Don't bet. You know that you will lose.

H(2) - Don't bet. You have no idea whether or not you will win.

H(3) - Uncertainty is high.

H(4) - Uncertainty is high.

If you are betting on each match, then bet only when uncertainty of Tiger winning is fairly low. Therefore, we need to draw a line at some point. When uncertainty is below this threshold, we bet knowing that the chances of winning are fairly high compared to the chances of winning when entropy is above this threshold. In our example, we choose .650 to be our threshold. When entropy is .650 or below, we are certain that we have a high probability of winning.

Problem No. 3

(a)

$$\begin{aligned}
H(X, Y) &= H(X) + H(Y|X) \\
H(X, Y) &= -\sum_x \sum_y p(x, y) \log p(x, y) \\
&= -\sum_x \sum_y p(x, y) \log p(x) p(y|x) \\
&= -\sum_x \sum_y p(x, y) \log p(x) - \sum_x \sum_y p(x, y) \log p(y|x) \\
&= -\sum_x p(x) \log p(x) - \sum_x \sum_y p(x, y) \log p(y|x) \\
&= H(X) + H(Y|X)
\end{aligned}$$

(b)

$$\begin{aligned}
H(X_1 X_2 \dots X_n) &= \sum_{i=0}^n H(X_i | X_{i-1} \dots X_1) \\
&= H(X_0) + H(X_1 | X_0) + H(X_2 | X_1, X_0) + \dots + H(X_n | X_{n-1}, X_{n-2}, \dots, X_0)
\end{aligned}$$

However, the dog's next step depends only on his previous two steps. The previous step gives us the direction in which the dog is traveling, and the step before the previous tells us whether or not the dog changed directions. This gives us a second order Markov chain.

$$H(X_0 X_1 \dots, X_n) = H(X_0) + H(X_1 | X_0) + \sum_{i=0}^n H(X_i | X_{i-1}, X_{i-2})$$

$H(X_0) = 0$ There is no uncertainty about the dog's starting position.

$H(X_1|X_0) = 1$ The dog's first step is equally likely to be positive or negative.

$$\sum_{i=2}^n H(X_i|X_{i-1}X_{i-2}) = (n-1)H(0.1, 0.9)$$

After the first step, there are $n-1$ steps left. The entropy is based on whether the dog continues forward with a probability of 0.9 or reverses direction with a probability of 0.1.

Thus,

$$H(X_0, X_1, \dots, X_n) = 1 + (n-1)H(0.1, 0.9)$$

(c)

$$\lim_{n \rightarrow \infty} \frac{H(X_0(X_1, \dots, X_n))}{n+1} = \frac{1 + (n-1) \cdot H(0.1, 0.9)}{n+1}$$

$$= H(0.1, 0.9) = 0.1 \log(1/0.1) + 0.9 \log(1/0.9) = 0.469 \text{ bits}$$

(d)

$$E[X] = \sum_{x \in \chi} x_i p(x)$$

$p =$ probability of forward step $= 0.9$

$q =$ probability of reverse step $= 0.1$

$q = 1 - p$

In s steps, the dog takes $s-1$ forward steps and 1 reverse step. Therefore, the probability of the dog walking forward and then reversing is:

$$p(x) = p^{s-1} q$$

$$E[S] = \sum_{s=1}^n s p^{s-1} q = \sum_{s=1}^n s p^s p^{-1} q = \frac{q}{p} \sum_{s=1}^n s p^s$$

$$\left(\sum_{n=1}^{\infty} n r^n = \frac{r}{(1-r)^2} \right)$$

$$E[S] = \frac{q}{p} \frac{p}{(1-p)^2} = \frac{q}{p} \frac{p}{q^2} = \frac{1}{q} = \frac{1}{0.1} = 10$$

Starting from zero, the expected number of steps before reversing direction is 11.